



The future of weather forecasting: high-resolution ensembles

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The olden days of weather forecasting



PLOTTING UPPER AIR MAPS

http://www.history.noaa.gov/stories_tales/women6.html

Modern weather forecasting



<http://www.nextgov.com/emerging-tech/2015/08/video-bringing-together-next-gen-weather-forecasters/119035/>

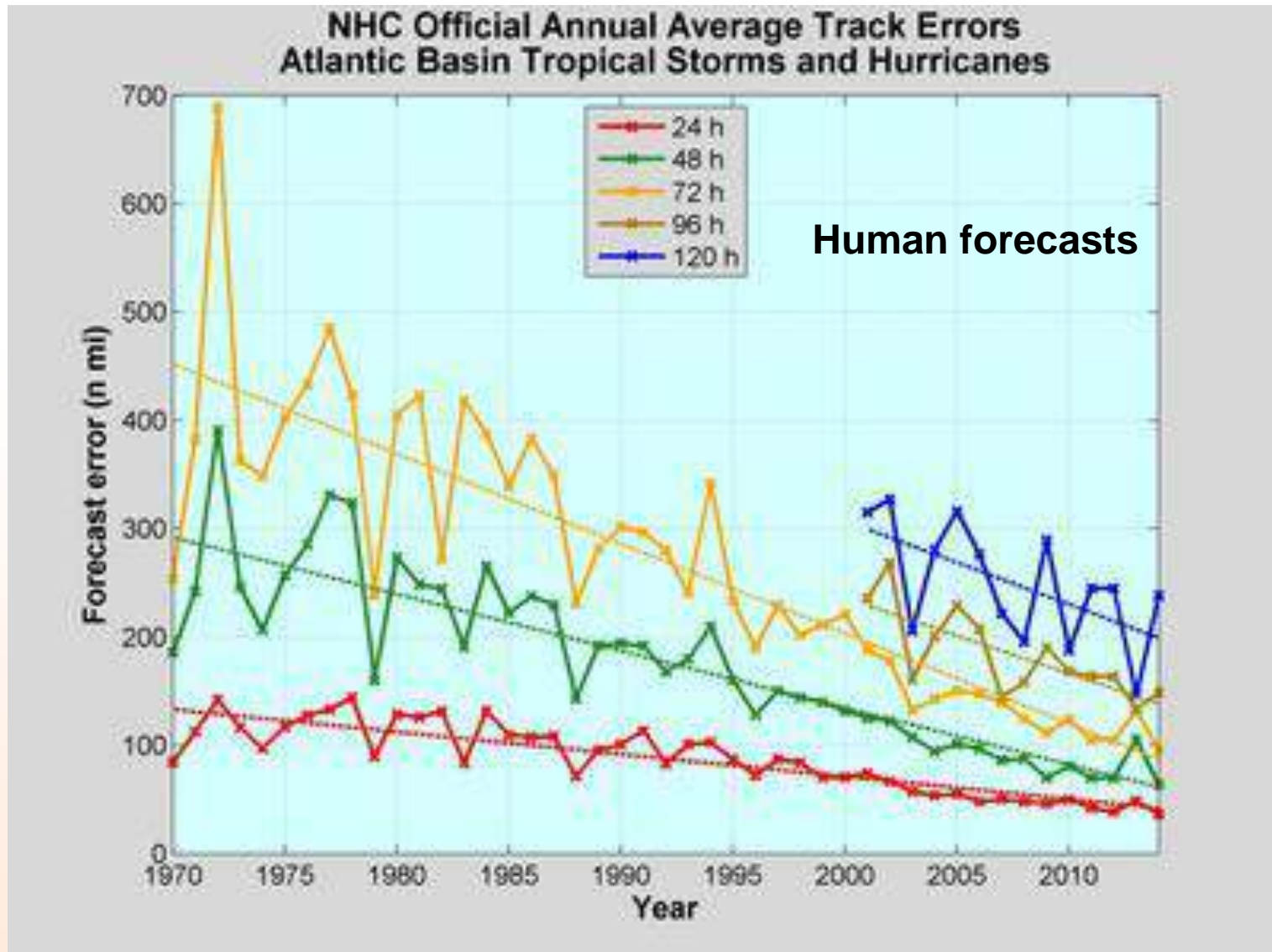


Supercomputer racks

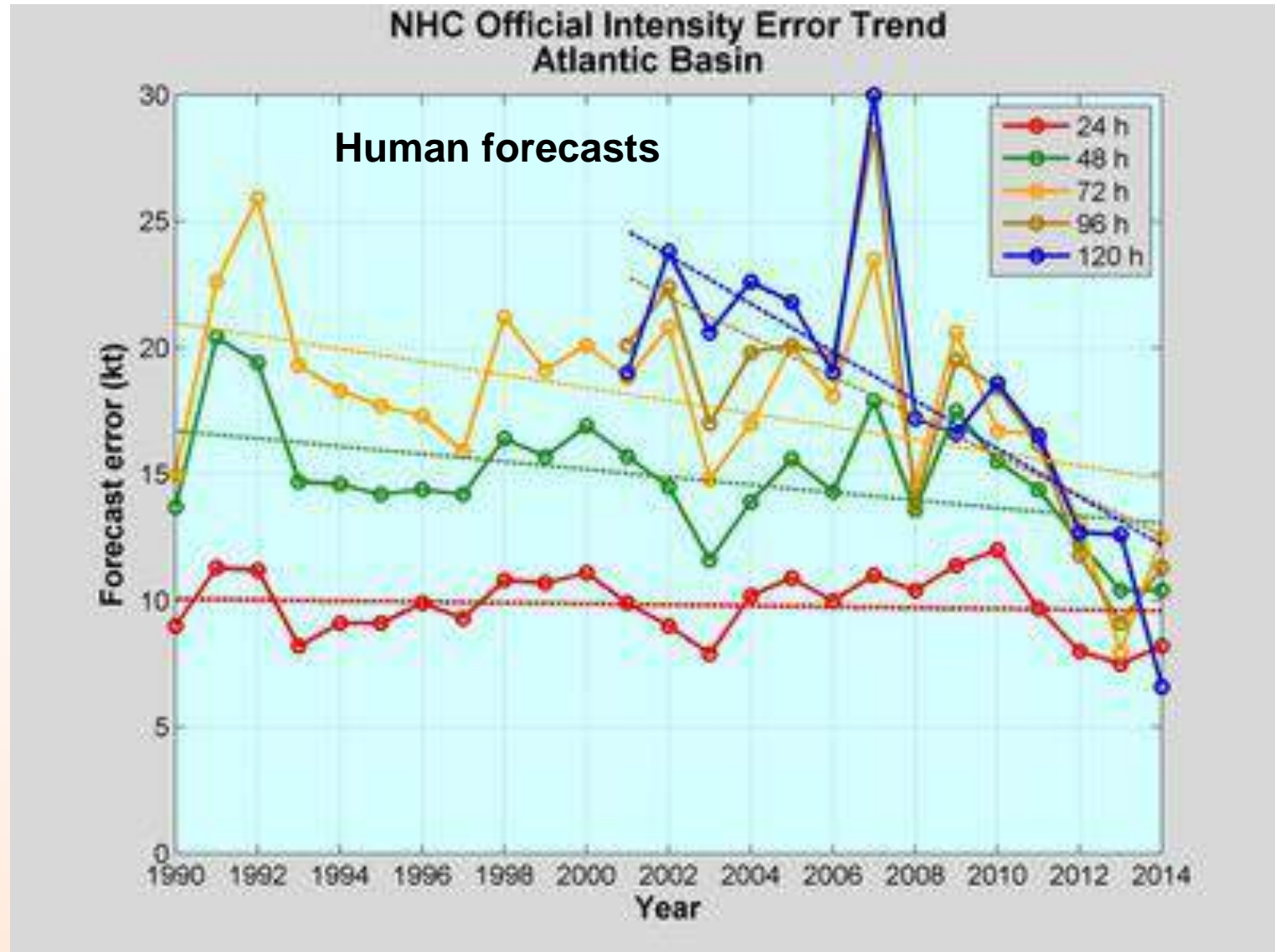
Weather forecasting has improved!

- Partly due to increases in computing, weather forecasting has greatly improved over the past few decades
- A happy marriage of computational and scientific progress

Atlantic Basin Hurricane Track Forecasts



Atlantic Basin Hurricane Intensity Forecasts



Components of a numerical weather prediction (NWP) model

- Initialization
 - Data assimilation
- Dynamics
- Physics
- Subjective choices
 - Horizontal resolution



Global Forecast System (GFS) resolution

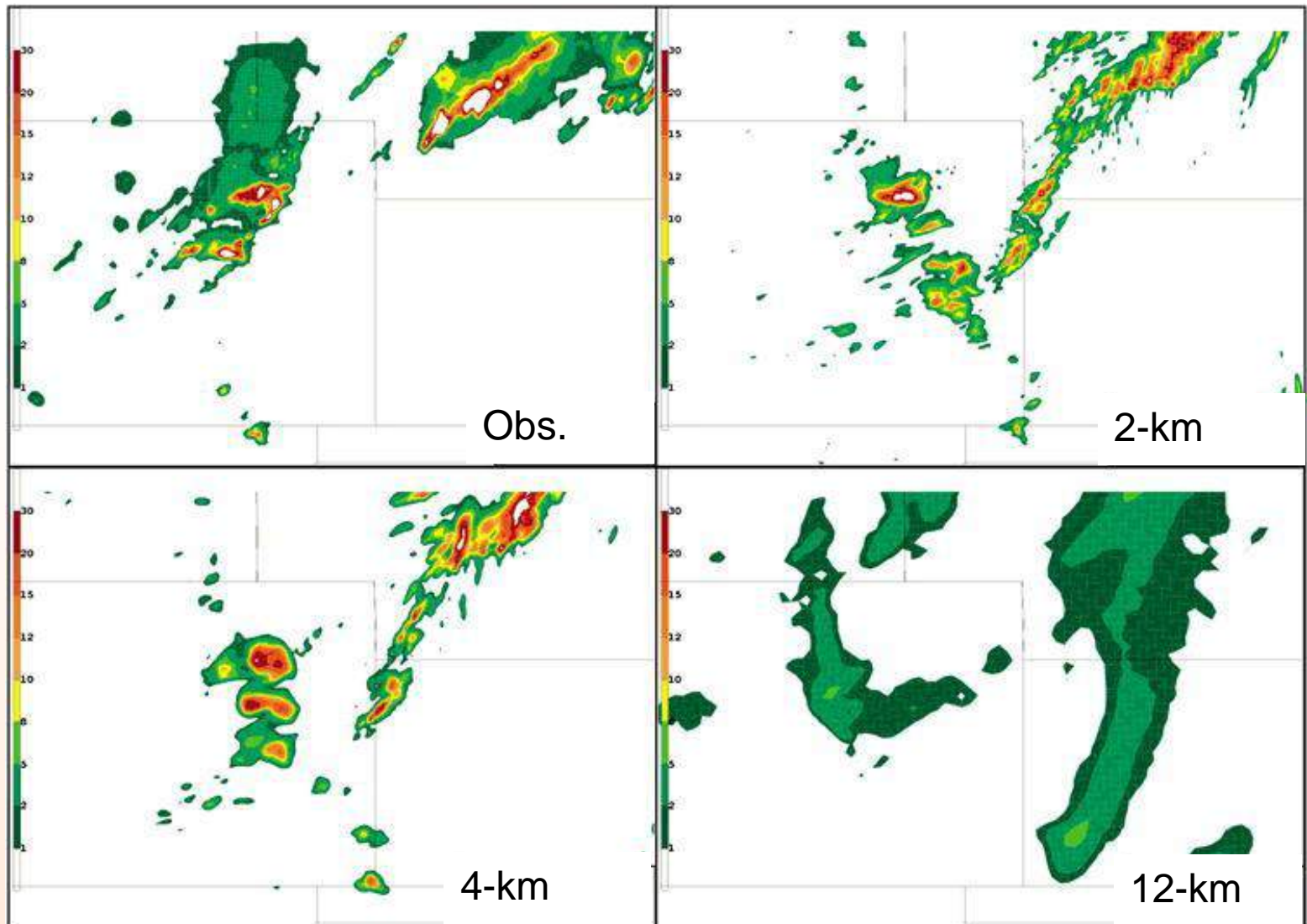
Steady increase
in horizontal
resolution with
time

| Year | Approximate horizontal grid spacing (km) | Number of vertical levels |
|------|--|---------------------------|
| 1980 | 375 | 12 |
| 1983 | 300 | 18 |
| 1987 | 150 | 18 |
| 1991 | 105 | 28 |
| 1998 | 80 | 42 |
| 2002 | 55 | 64 |
| 2005 | 35 | 64 |
| 2010 | 27 | 64 |
| 2015 | 13 | 64 |

High-resolution models

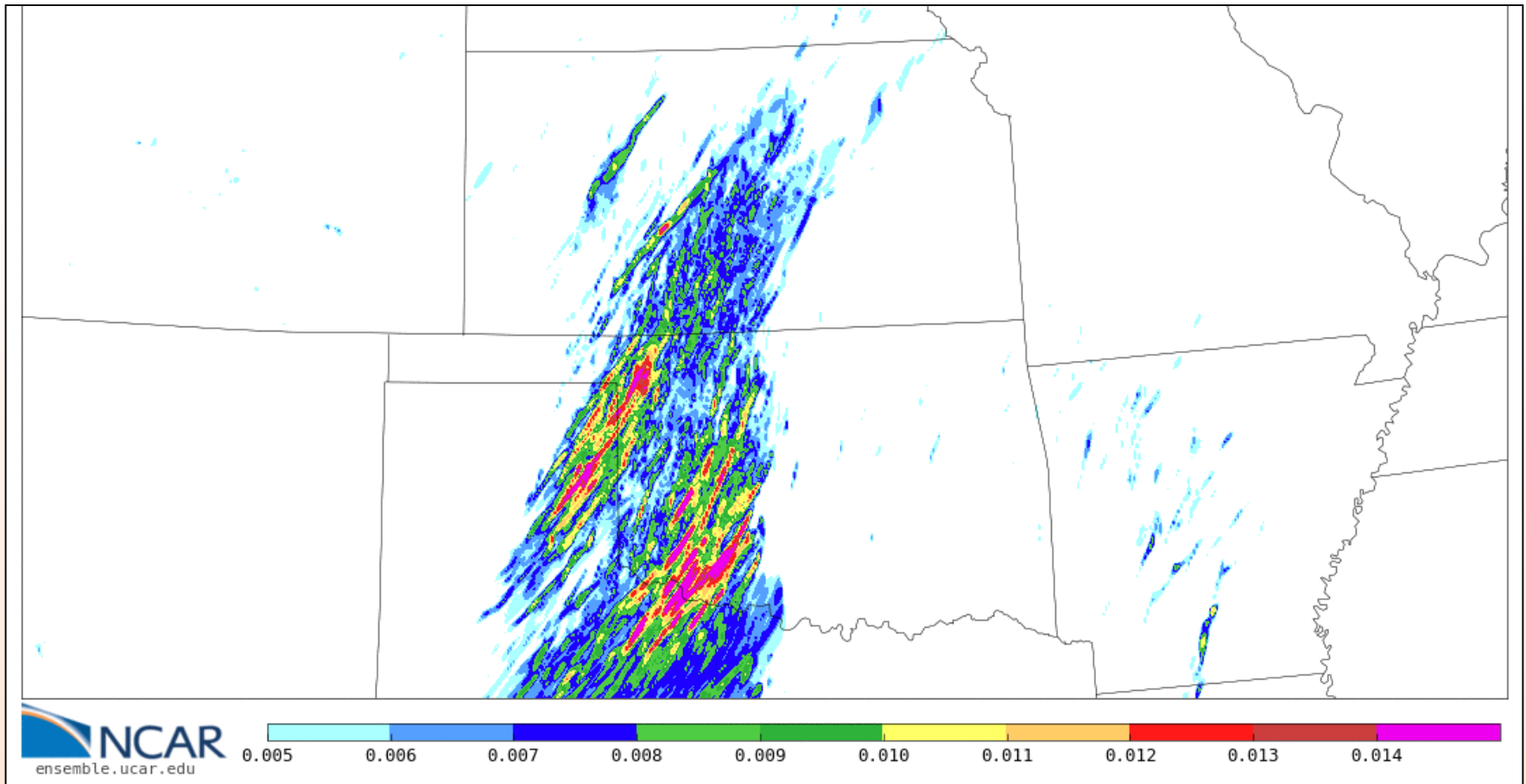
- Computer models are pretty good at predicting large-scale systems
- Challenges remain regarding finer-scale details
- To address these challenges, high-resolution models are needed
 - Typically have horizontal grid spacings of 1- to 4-km

Benefit of high-resolution



Cool high-resolution fields

- Maximum 1-km vertical vorticity over 7-hrs
 - Toward tornado prediction



Sensitivity to horizontal grid-spacing

- Within high-resolution model configurations, what resolution is really needed?
- Little dispute that higher-resolution means more realism
 - But does greater realism translate into greater value?
 - If a 4-km model is as useful as 2-km, is it worth the ~8-fold additional cost to have a 2-km model?





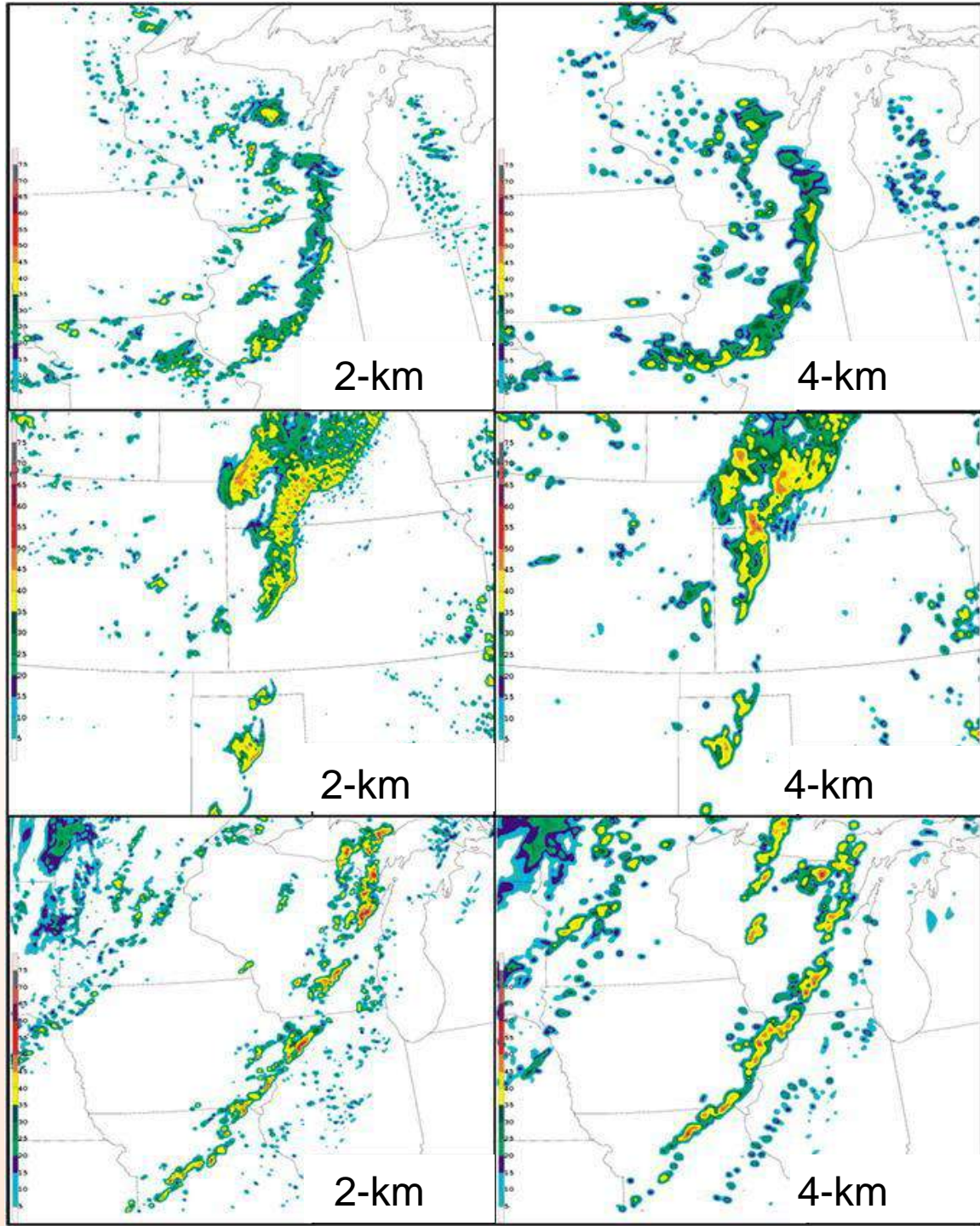








Simulated reflectivity snapshots



Convective evolution

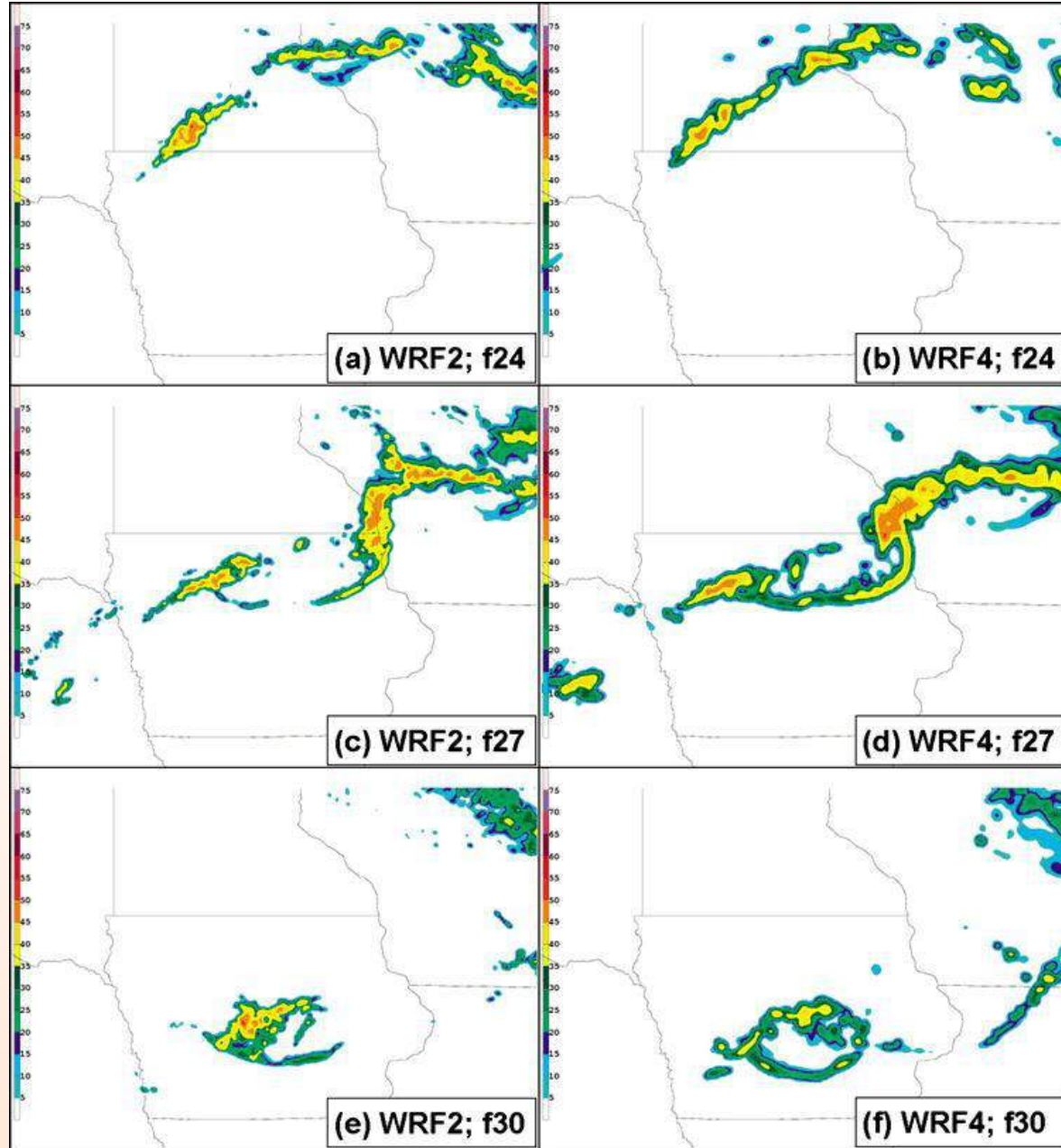
24-hr forecast

27-hr forecast

30-hr forecast

2-km

4-km

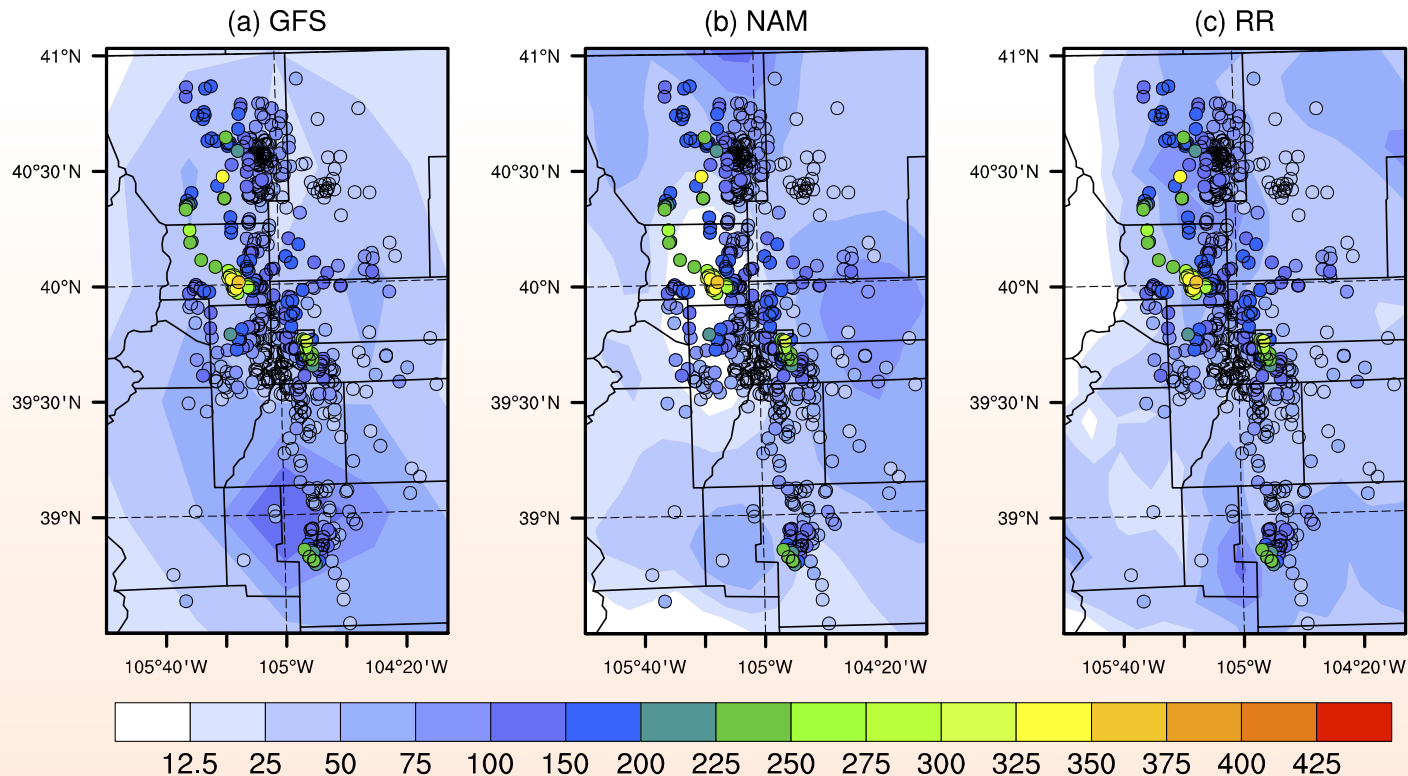


Colorado Front Range floods of 2013



Operational, coarse-resolution forecasts

- 48-hr accumulated precipitation
 - **NAM, GFS, and RR operational models**
 - CoCoRaHS gauge measurements overlaid



48-hr accumulated precipitation (mm) between 1200 UTC 11 and 1200 UTC 13 September

4-km WRF model forecasts

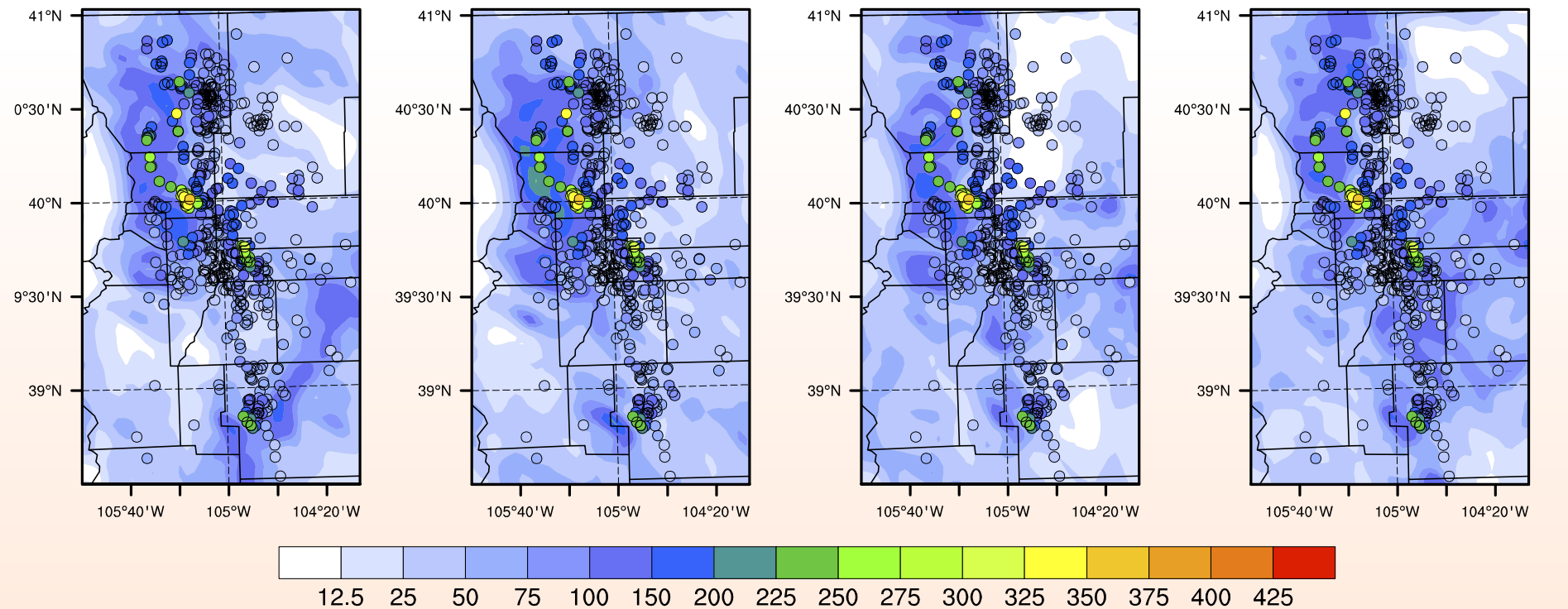
- 48-hr accumulated precipitation
- CoCoRaHS gauge measurements overlaid

(e) WRF4: GFS ICs, Thompson MP

(f) WRF4: GFS ICs, Morrison MP

(g) WRF4: NAM ICs, Thompson MP

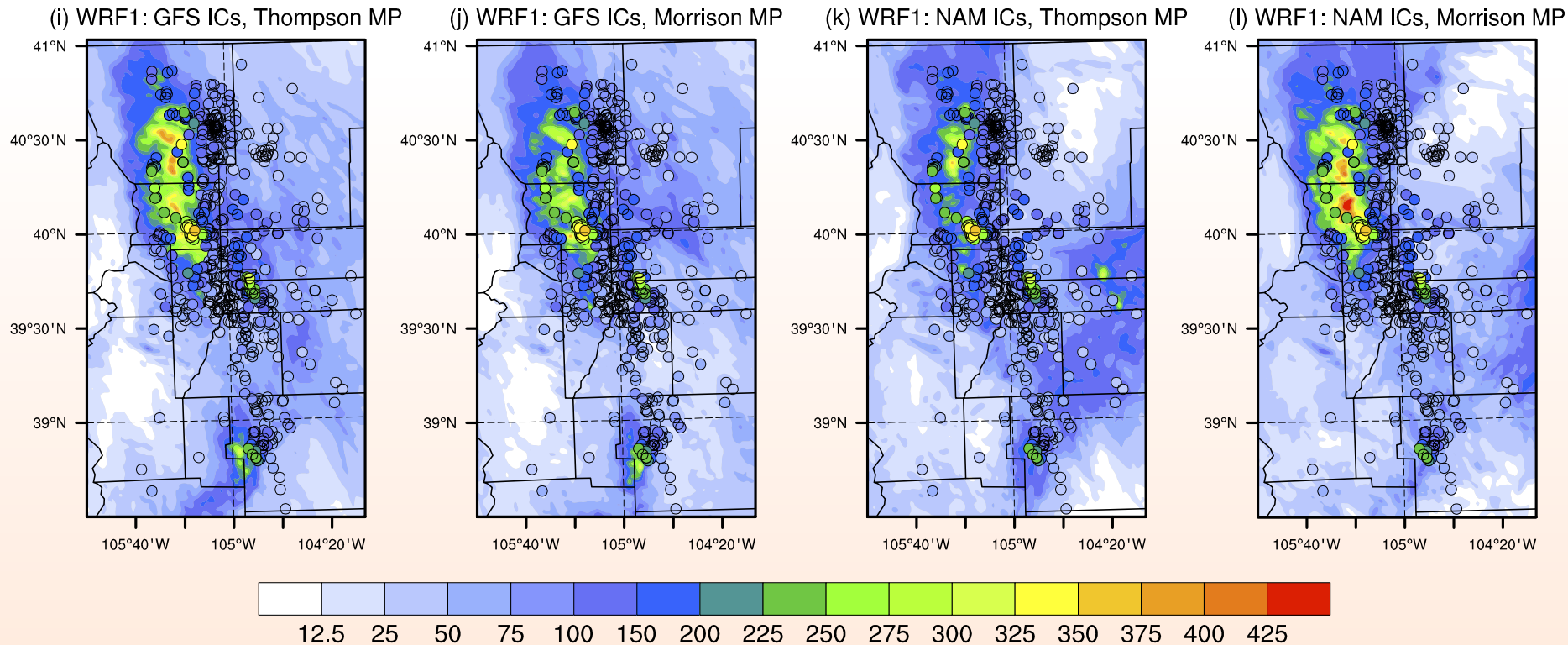
(h) WRF4: NAM ICs, Morrison MP



48-hr accumulated precipitation (mm) between 1200 UTC 11 and 1200 UTC 13 September

1-km WRF model forecasts

- 48-hr accumulated precipitation
- CoCoRaHS gauge measurements overlaid



48-hr accumulated precipitation (mm) between 1200 UTC 11 and 1200 UTC 13 September

Objective verification of high-resolution models

Traditional objective verification

- Verification at the **grid-scale**
- Pick an event
 - Precipitation exceeding 1.0 mm/hr
- Compare forecast and observations at each grid point

| | | Observed | | |
|----------|-----|----------|---------|---------|
| | | Yes | No | |
| Forecast | Yes | a | b | $a + b$ |
| | No | c | d | $c + d$ |
| | | $a + c$ | $b + d$ | |

Standard 2 x 2 contingency table for dichotomous events

Traditional point-by-point methods

- The event has occurred at the shaded grid points

Model output

| | | | | |
|---|---|---|---|---|
| + | + | + | + | + |
| + | + | + | + | + |
| + | + | + | + | + |
| + | + | + | + | + |
| + | + | + | + | + |

Observations

| | | | | |
|---|---|---|---|---|
| + | + | + | + | + |
| + | + | + | + | + |
| + | + | + | + | + |
| + | + | + | + | + |
| + | + | + | + | + |

Grid point classification

- Green: “hits”
- Red: “false alarms”
- Blue: “misses”
- White: “correct negatives”

Classification

| | | | | |
|---|---|---|---|---|
| + | + | + | + | + |
| + | + | + | + | + |
| + | + | + | + | + |
| + | + | + | + | + |
| + | + | + | + | + |

Model output

| | | | | |
|---|---|---|---|---|
| + | + | + | + | + |
| + | + | + | + | + |
| + | + | + | + | + |
| + | + | + | + | + |
| + | + | + | + | + |

Observations

| | | | | |
|---|---|---|---|---|
| + | + | + | + | + |
| + | + | + | + | + |
| + | + | + | + | + |
| + | + | + | + | + |
| + | + | + | + | + |

It's a beautiful day in the "neighborhood"

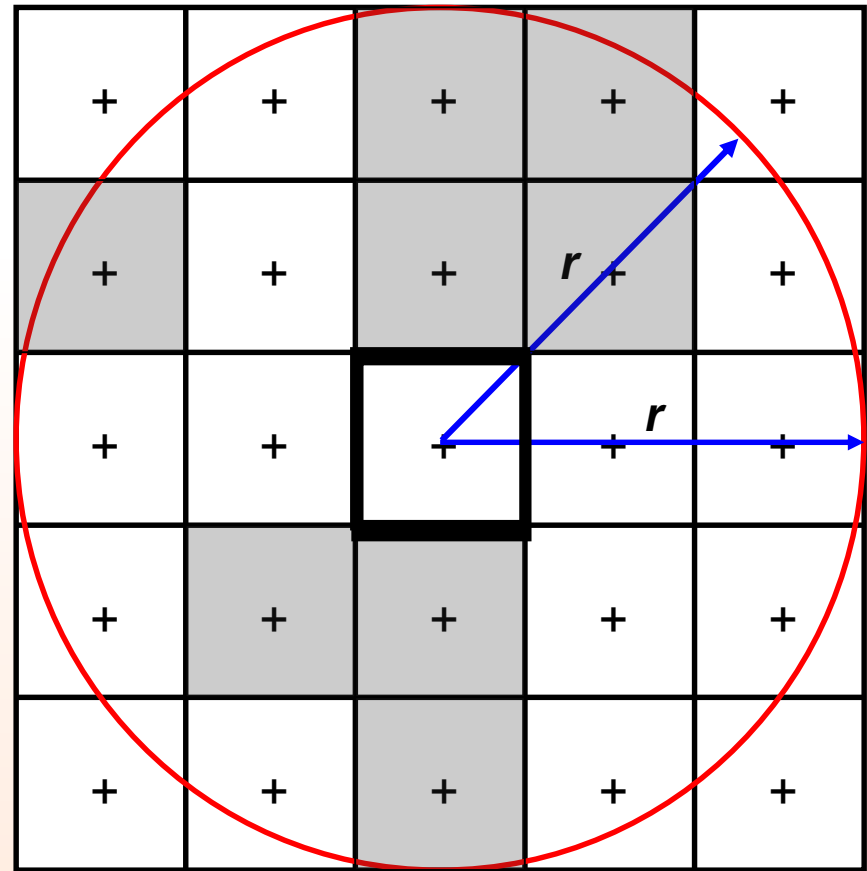


- High-resolution models are not accurate at the grid scale
- To account for spatial displacement errors, specify a radius of influence (r) about each grid point
- Define an event
- Generate a probability at each grid point

Schematic Example

- $r = 2.5$ times the grid spacing
- The event has occurred in the shaded boxes
- Event occurs in 8 boxes
- 21 total boxes in neighborhood

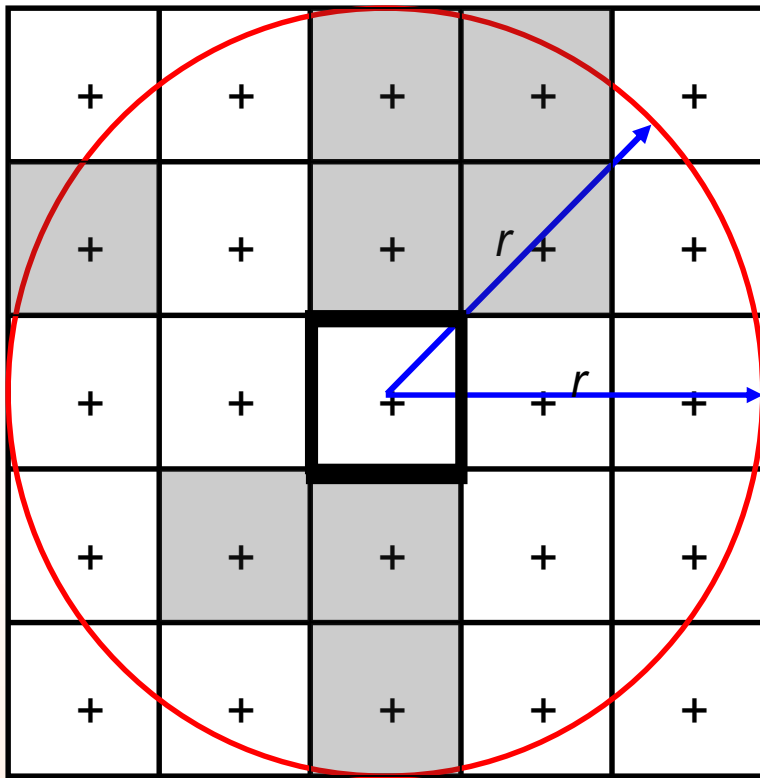
Hypothetical model output



$$P = 8/21 = 38\%$$

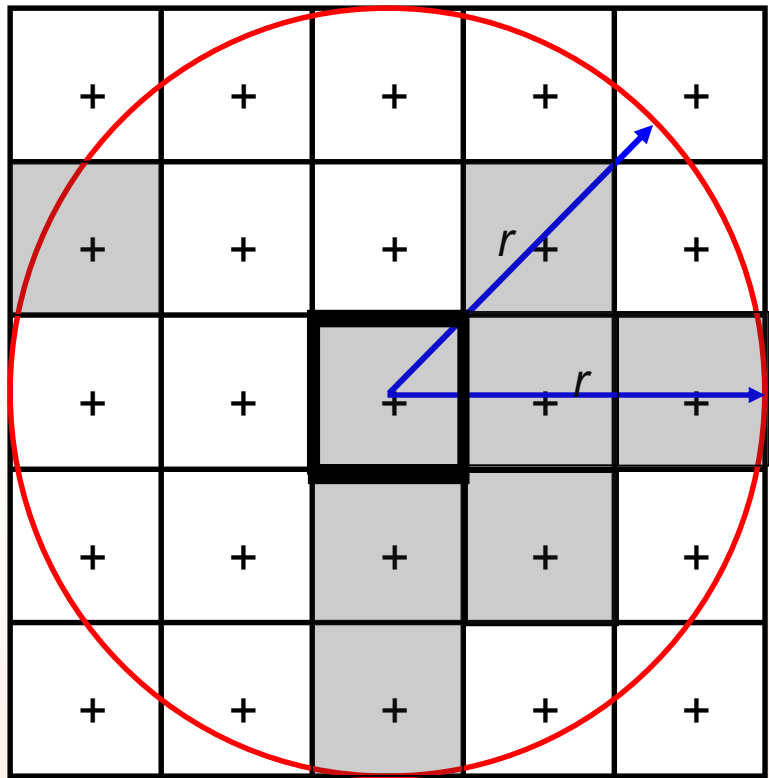
Example Applied to Model and Observations

Model output



$$P = 8/21 = 38\%$$

Observations



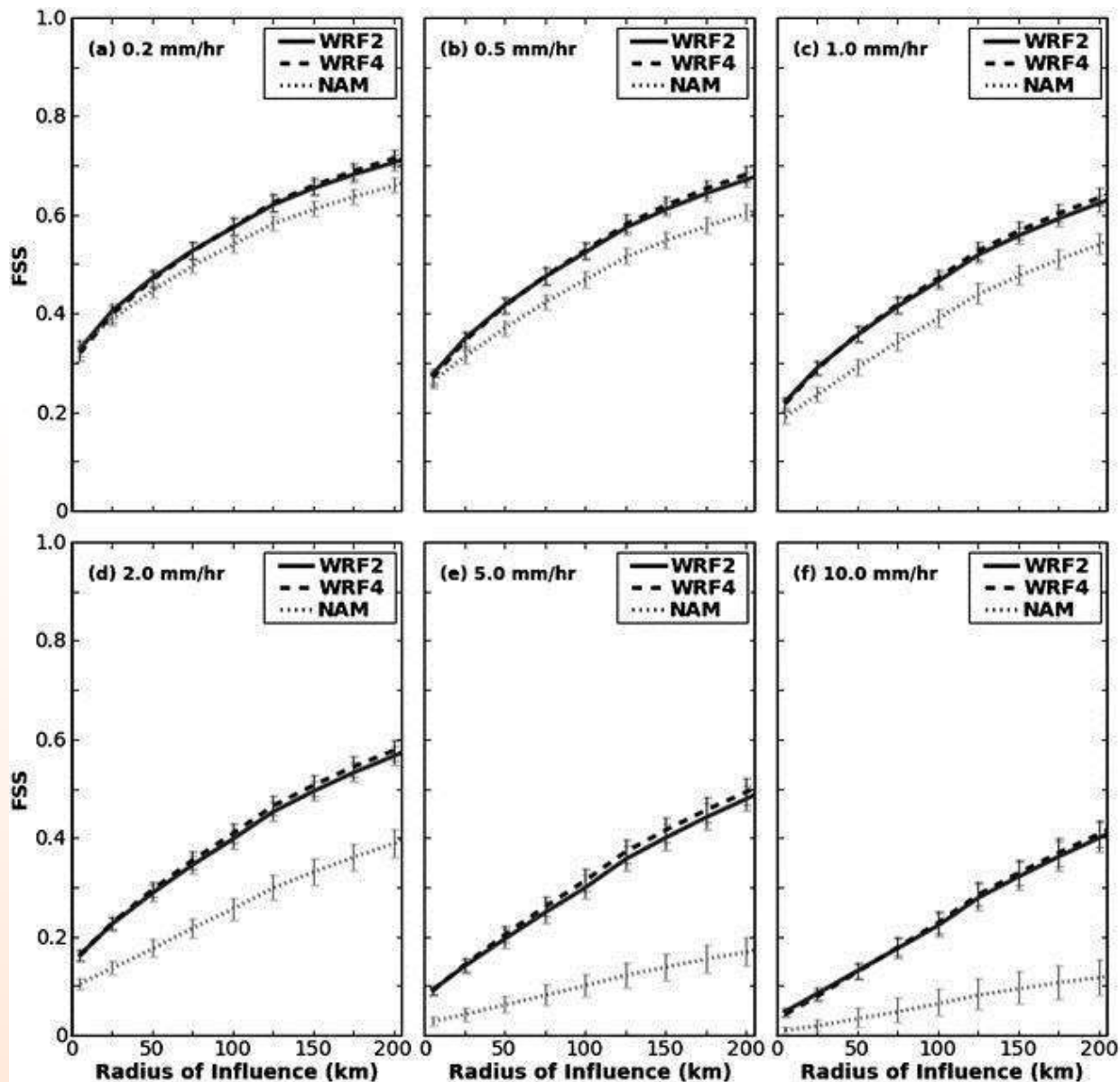
$$P = 8/21 = 38\%$$

A perfect forecast using this neighborhood approach

Objective benefit of high-resolution

The fractions skill score compares observed and forecast fractions

WRF2: 2-km
WRF4: 4-km
NAM: 12-km



Thoughts about horizontal grid spacing

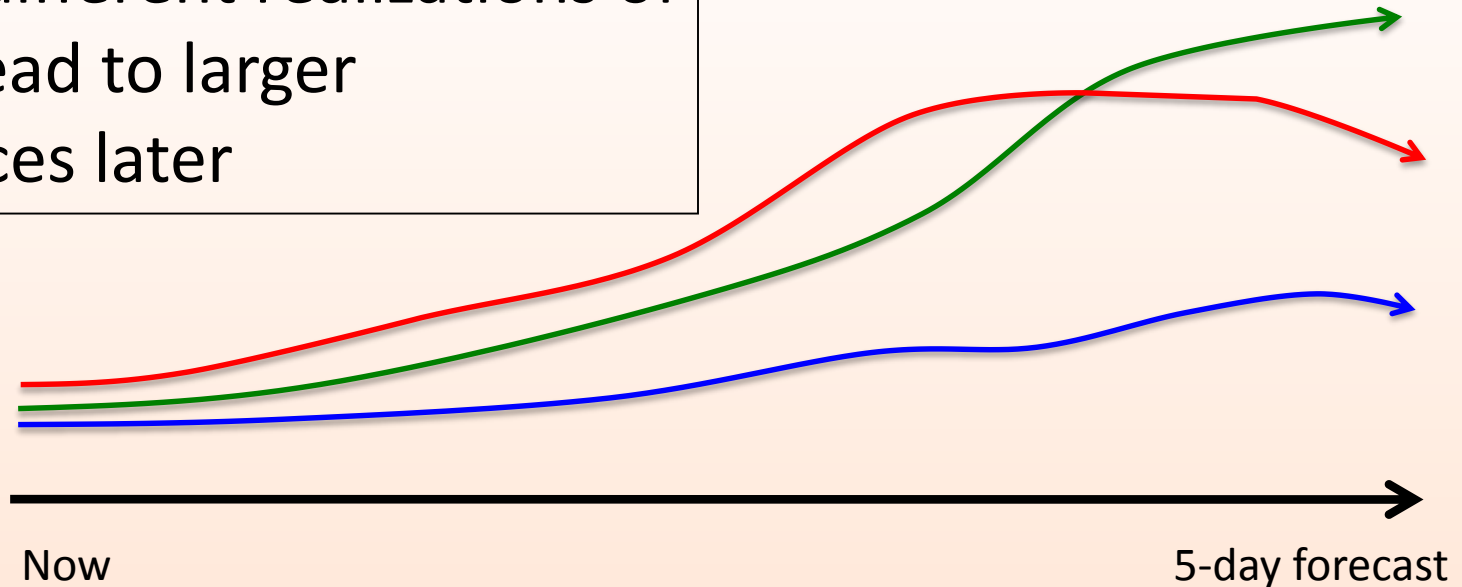
- It appears that 3- or 4-km horizontal grid spacing provides similar value and accuracy as 1- or 2-km horizontal grid spacing over flat terrain
 - Higher-resolution always provides more realism
- In topographically-diverse areas, higher-resolution (~1-km horizontal grid spacing) is usually better

Ensemble prediction systems

Probabilistic predictions

- Probabilistic forecasts are often generated by **ensembles** of computer models, where variations in model parameters yield different forecast outcomes
- Different forecasts are called “**ensemble members**”

Slightly different realizations of “now” lead to larger differences later

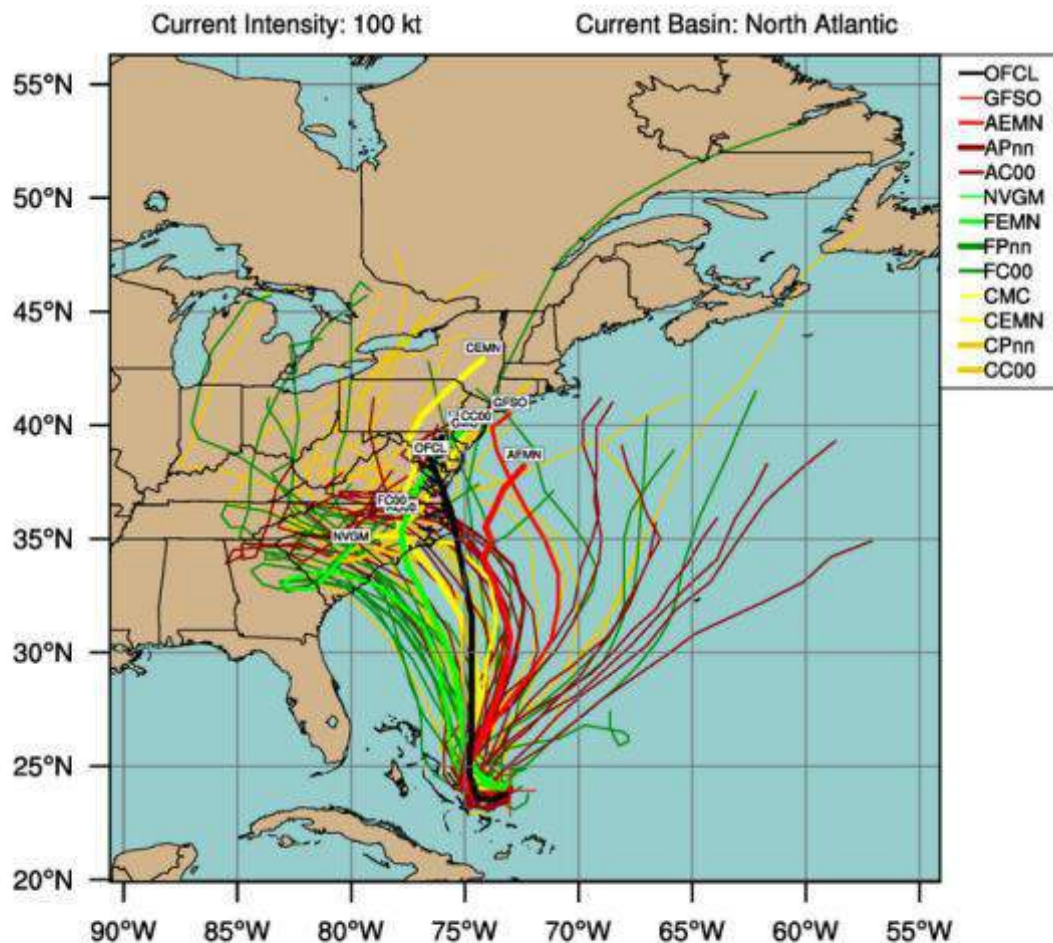


Hurricane Joaquin

MAJOR HURRICANE JOAQUIN (AL11)

EPS track guidance initialized at 0000 UTC, 01 October 2015

Hurricane Joaquin had a very uncertain track



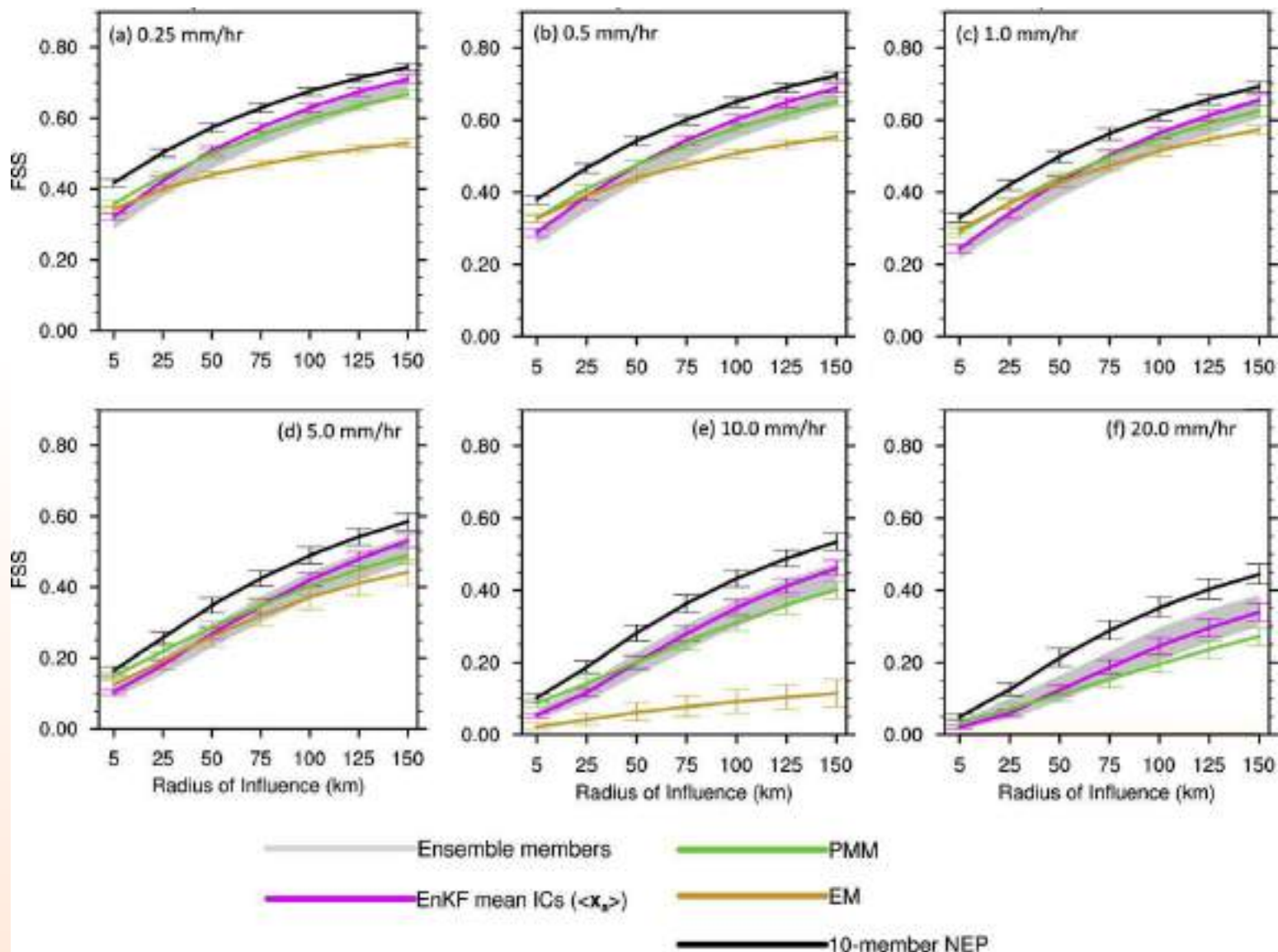
By using this plot, the user agrees to the UCAR Terms of Use which can be accessed at: <http://www2.ucar.edu/terms-of-use>

Plot generated at 0922 UTC 01 October 2015

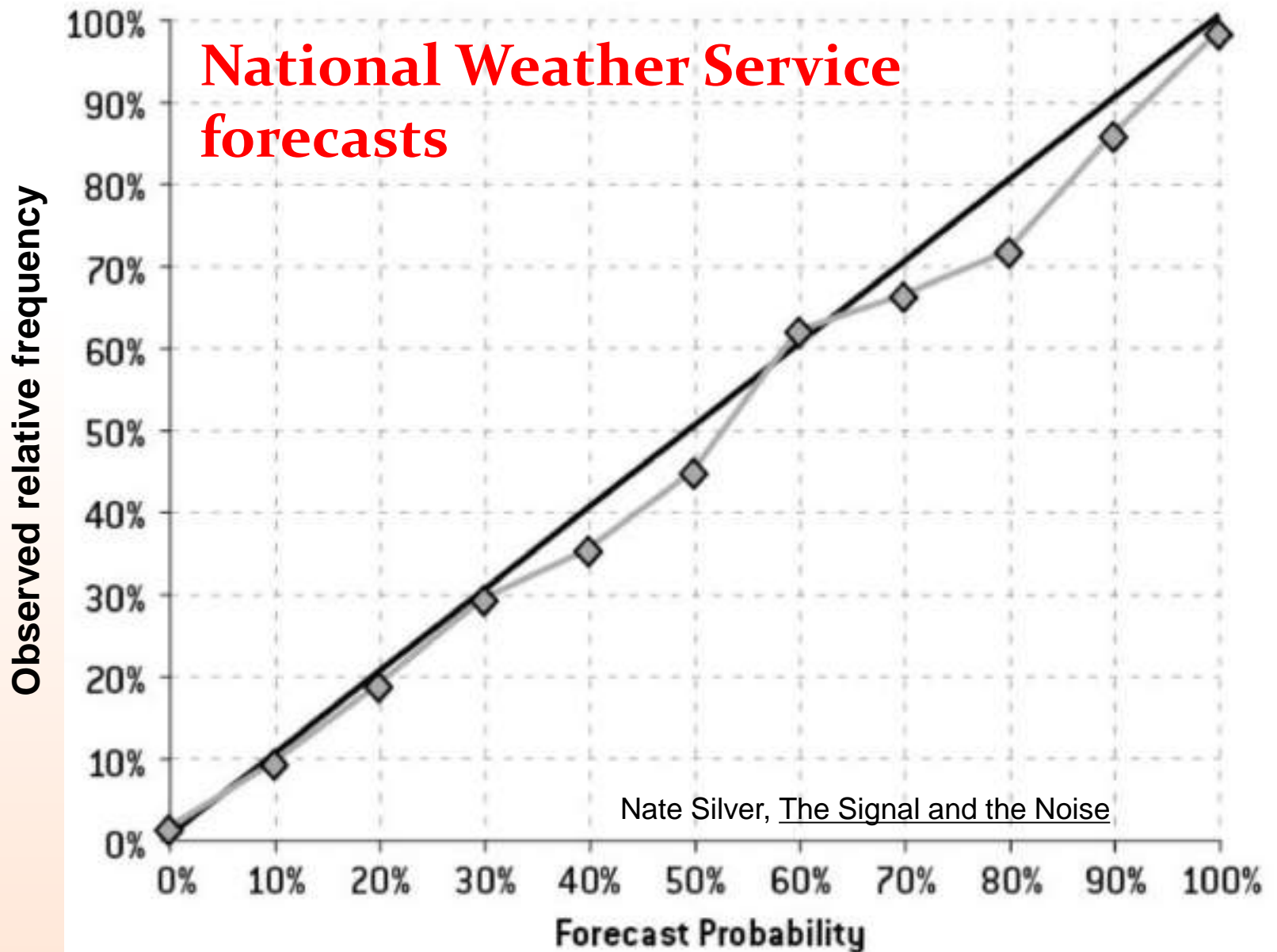
Why ensemble forecasts are desirable

- Quantification of uncertainty
 - Naturally produces probabilities!
 - Allows forecasters to forecast their “true beliefs”
 - Allows users to make decisions based on expected value and cost-loss scenarios
- Errors of different members cancel when combining forecasts across members
 - Forecasts combining information across all members are better than single deterministic forecasts

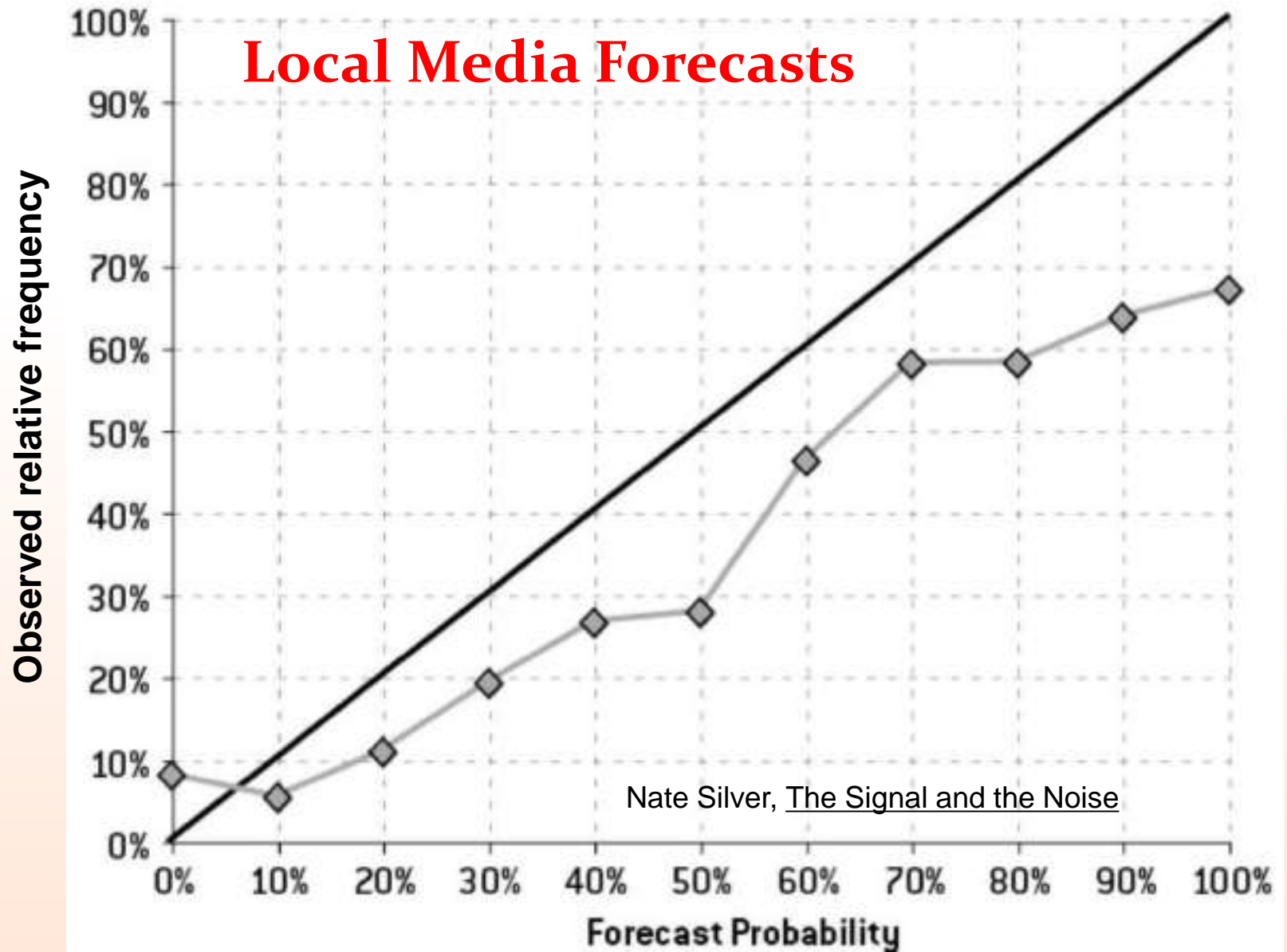
Ensembles are better



Ensemble verification: Calibration



Calibration



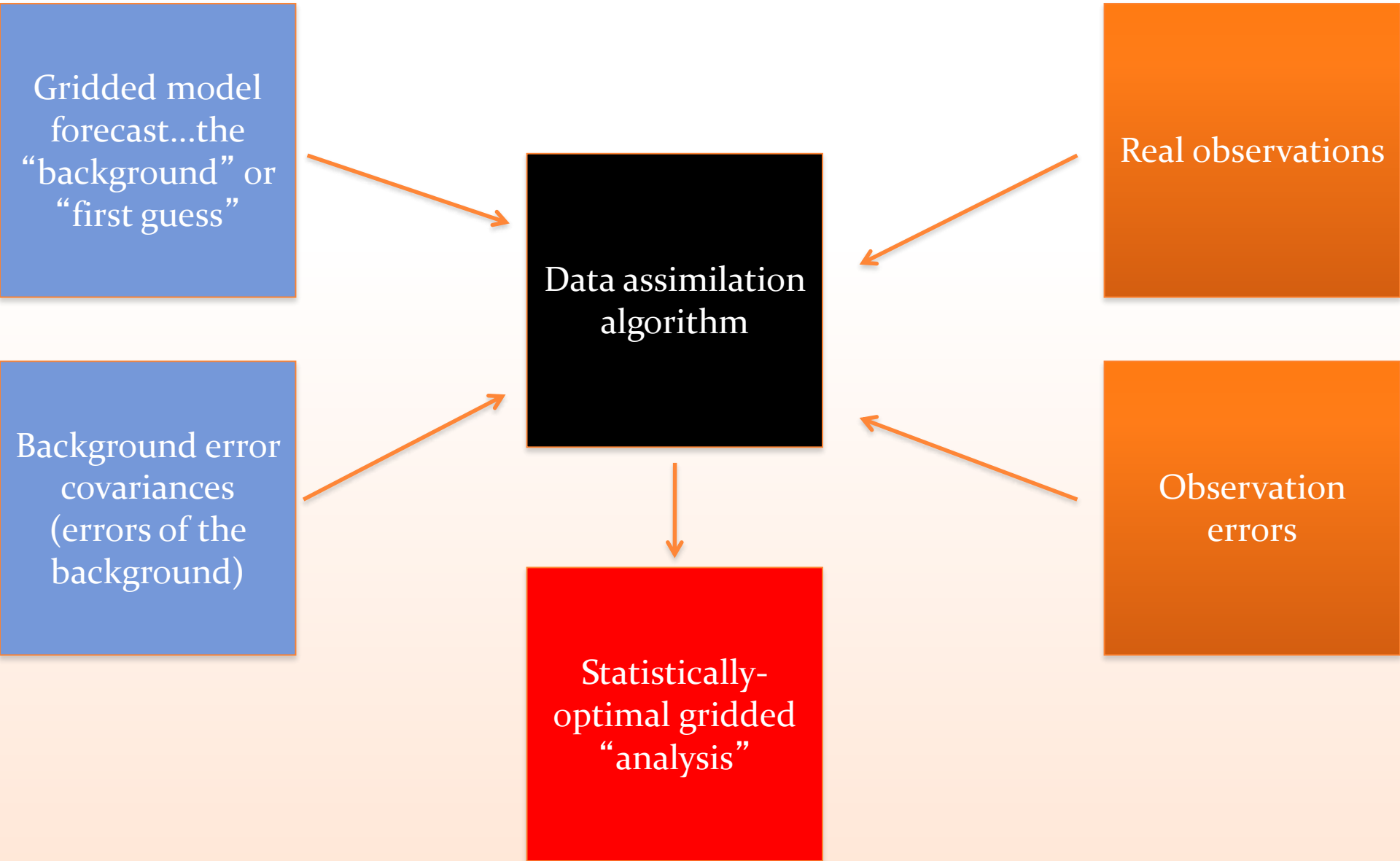
Challenge with high-resolution ensembles

- One of the forefronts of NWP model research is how to design high-resolution ensembles
 - Vary just initial conditions?
 - Configure different members with different physics or dynamics?
- Each method has advantages and disadvantages
- General goal is to improve calibration

How to initialize high-resolution ensembles?

- Use existing operational ensembles
 - Cheap and easy but potential for mismatches
- Add random noise to a single field
 - A bit ad hoc
- Use **ensemble data assimilation**

What is data assimilation?



Two (of many) data assimilation approaches

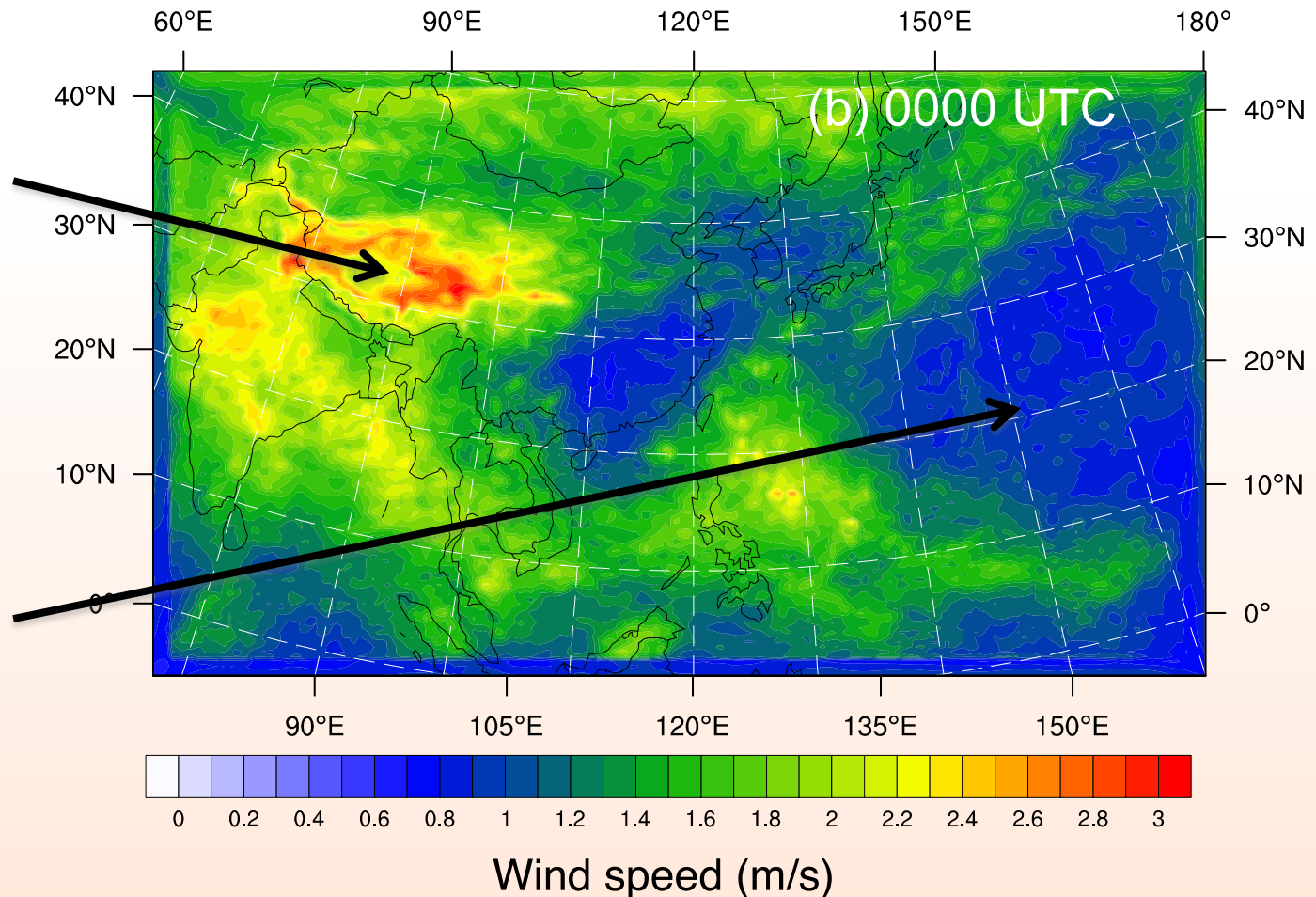
- Three-dimensional variational (3DVAR)
 - Background error covariances (BECs) typically fixed/time-invariant
 - May yield poor results when actual flow differs from that encapsulated within the fixed “climatology”
- Ensemble Kalman filter (EnKF)
 - Time-evolving, “flow-dependent” BECs estimated from a short-term ensemble forecast

Background errors and observations

- Ensemble spread (standard deviation) of wind speed

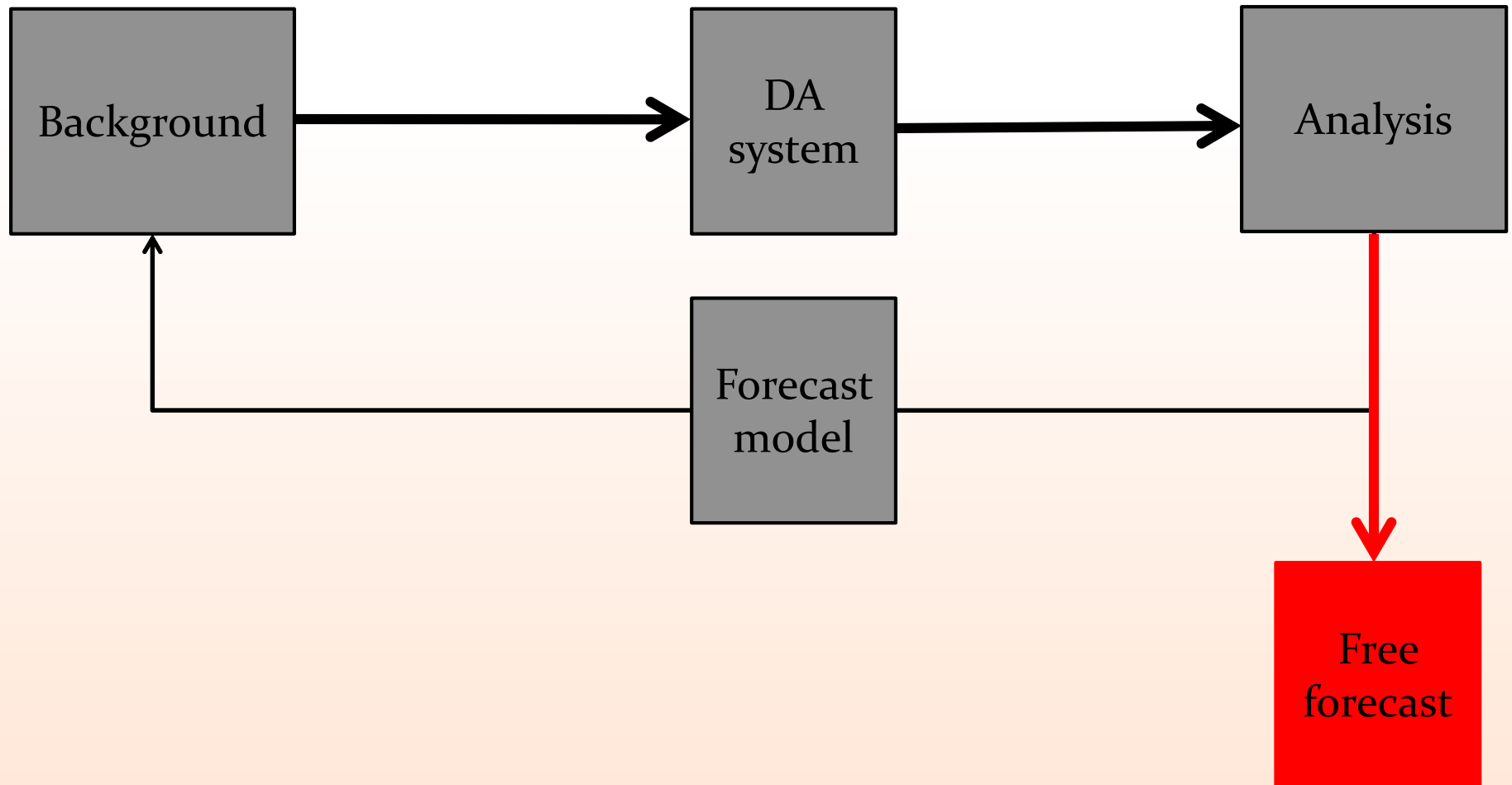
More model uncertainty:
give observations more weight

Less model uncertainty:
give observations less weight



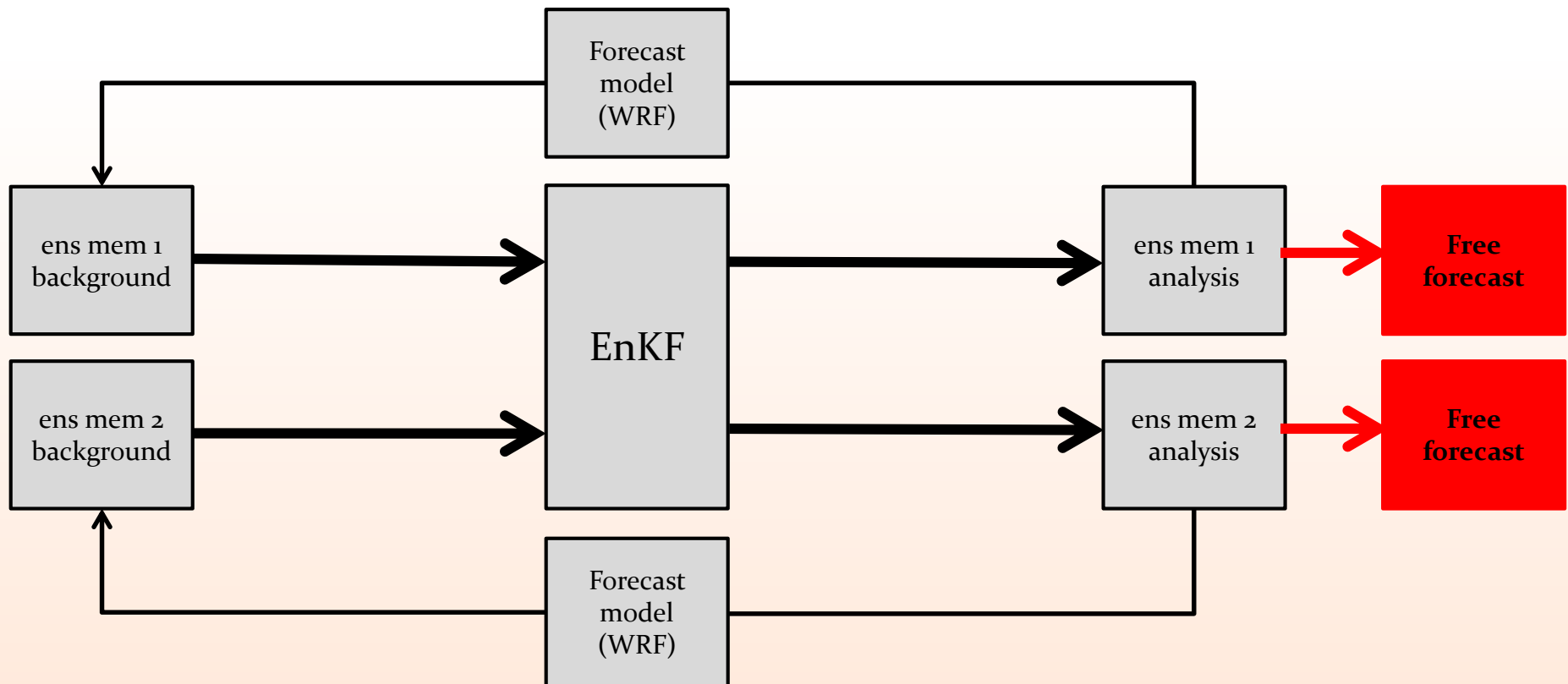
Continuously cycling data assimilation

- Usually 1- to 6-hrs between each analysis



Continuously cycling EnKF

- Initial conditions for all ensemble members are dynamically consistent
 - No ad hoc assumptions or use of external models

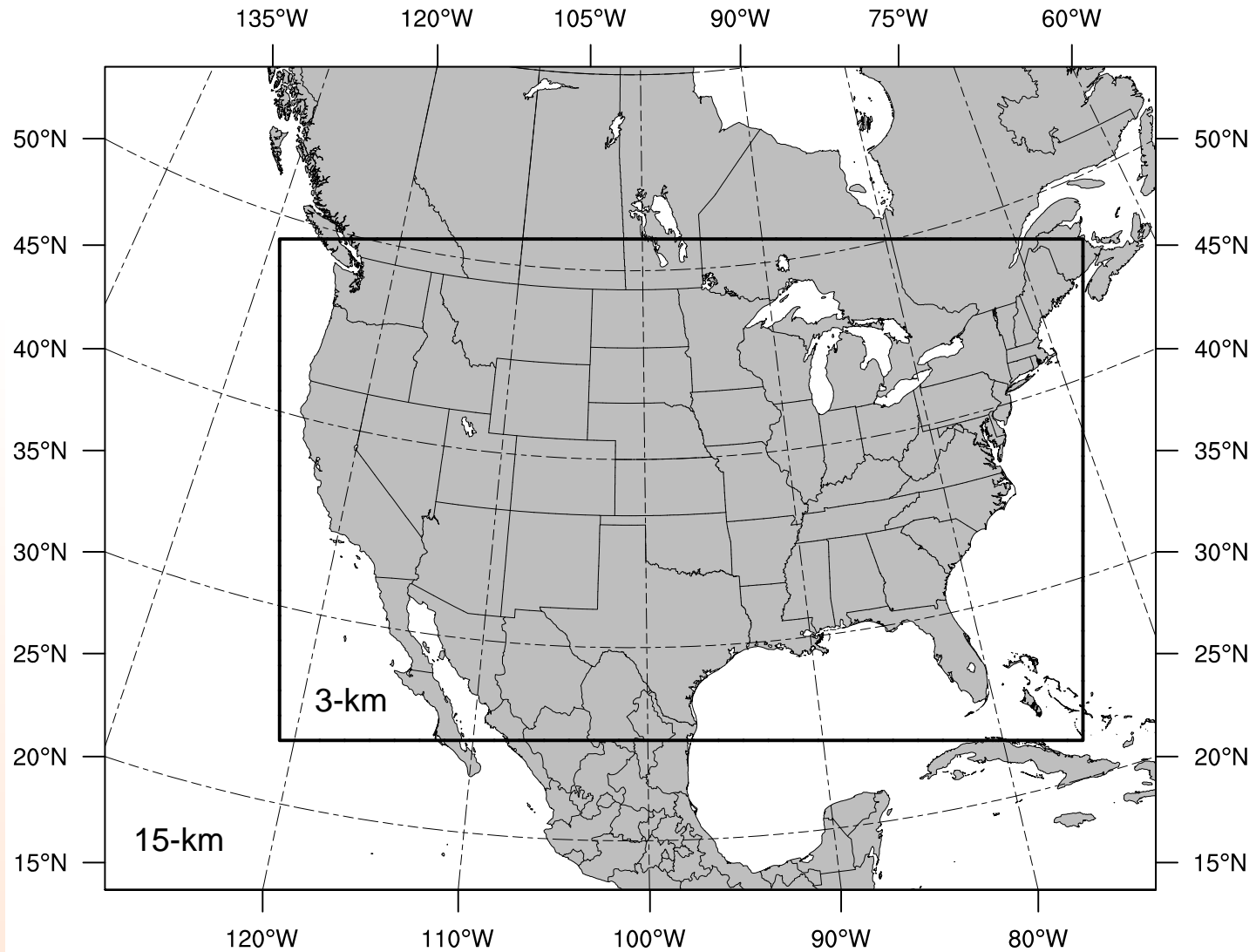


What we're doing at NCAR/MMM

- Since April 7, 2015, we have been producing real-time, 10-member ensemble forecasts
 - 3-km horizontal grid spacing
- 50-member continuously cycling EnKF
 - 15-km horizontal grid spacing
 - New analysis every 6-hrs
 - Initializes the 10-member, 3-km ensemble forecasts
 - Use of EnKF to initialize high-resolution ensembles is unique

<http://www.ensemble.ucar.edu>

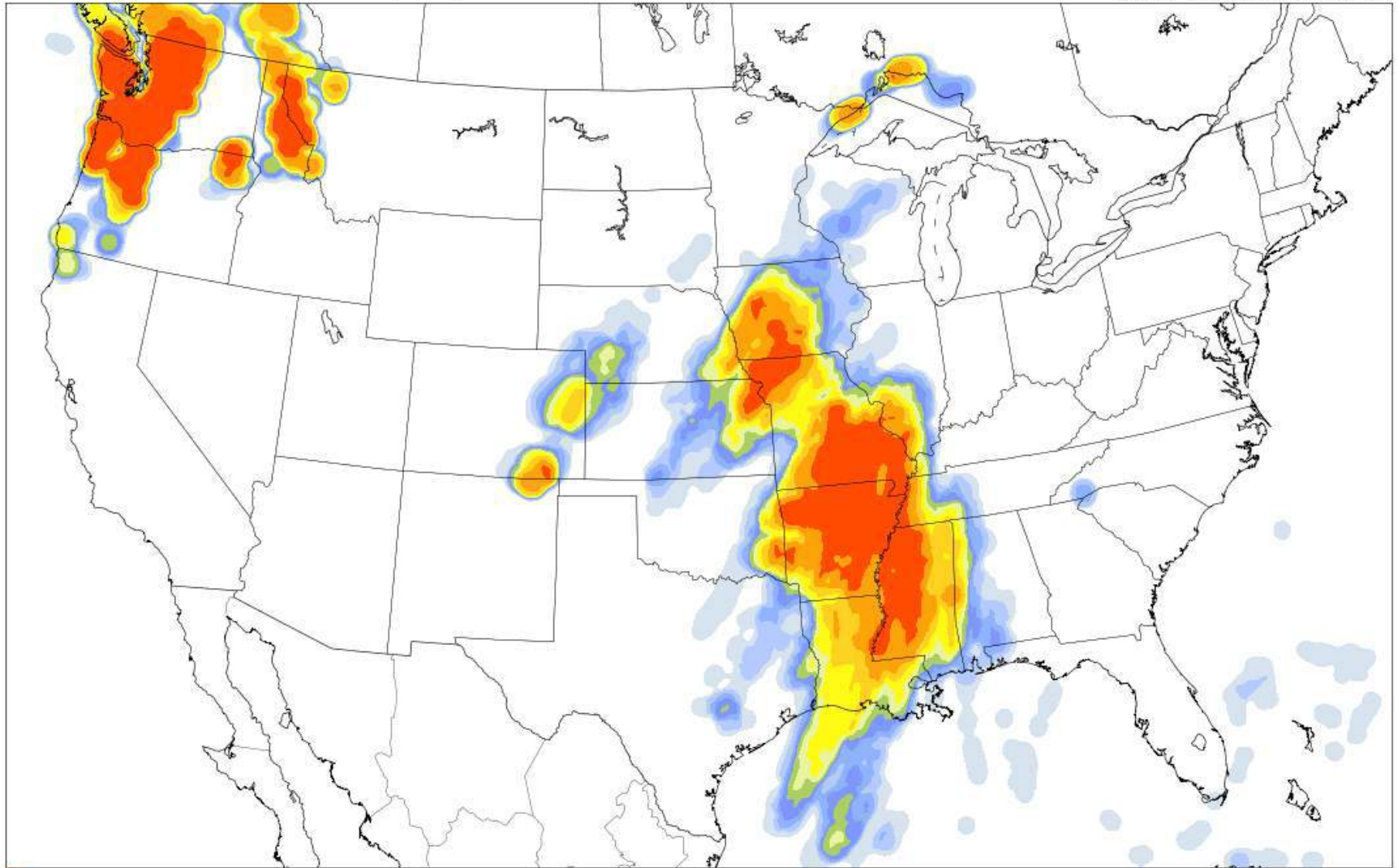
NCAR ensemble domain



Heavy precipitation probabilities

Probability of 48-hr accumulated precipitation > 3.0 in within 25-mi

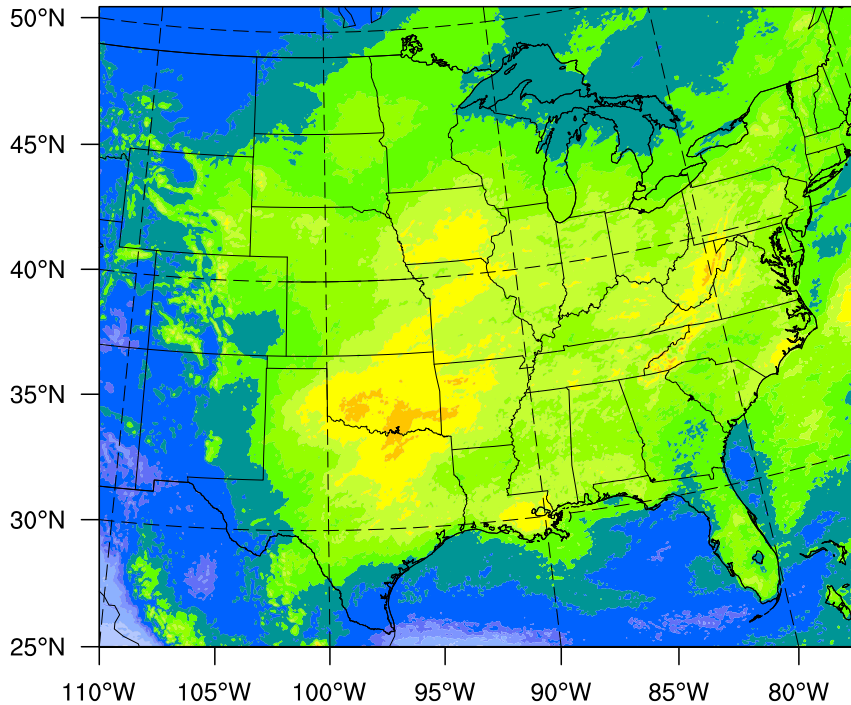
Init: Tue 2015-11-17 00 UTC
Valid: Thu 2015-11-19 00 UTC



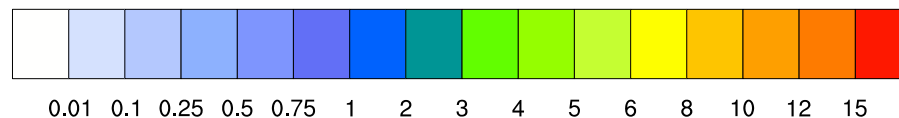
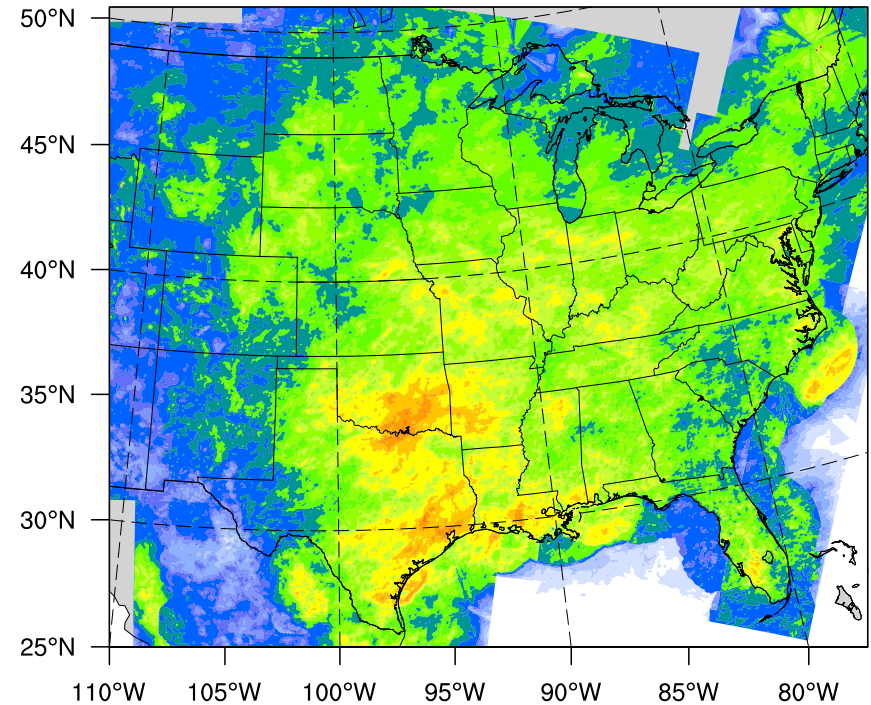
General precipitation placement

- Average 12-36-hr ensemble mean precipitation between April 7 and July 5, 2015

Ensemble mean



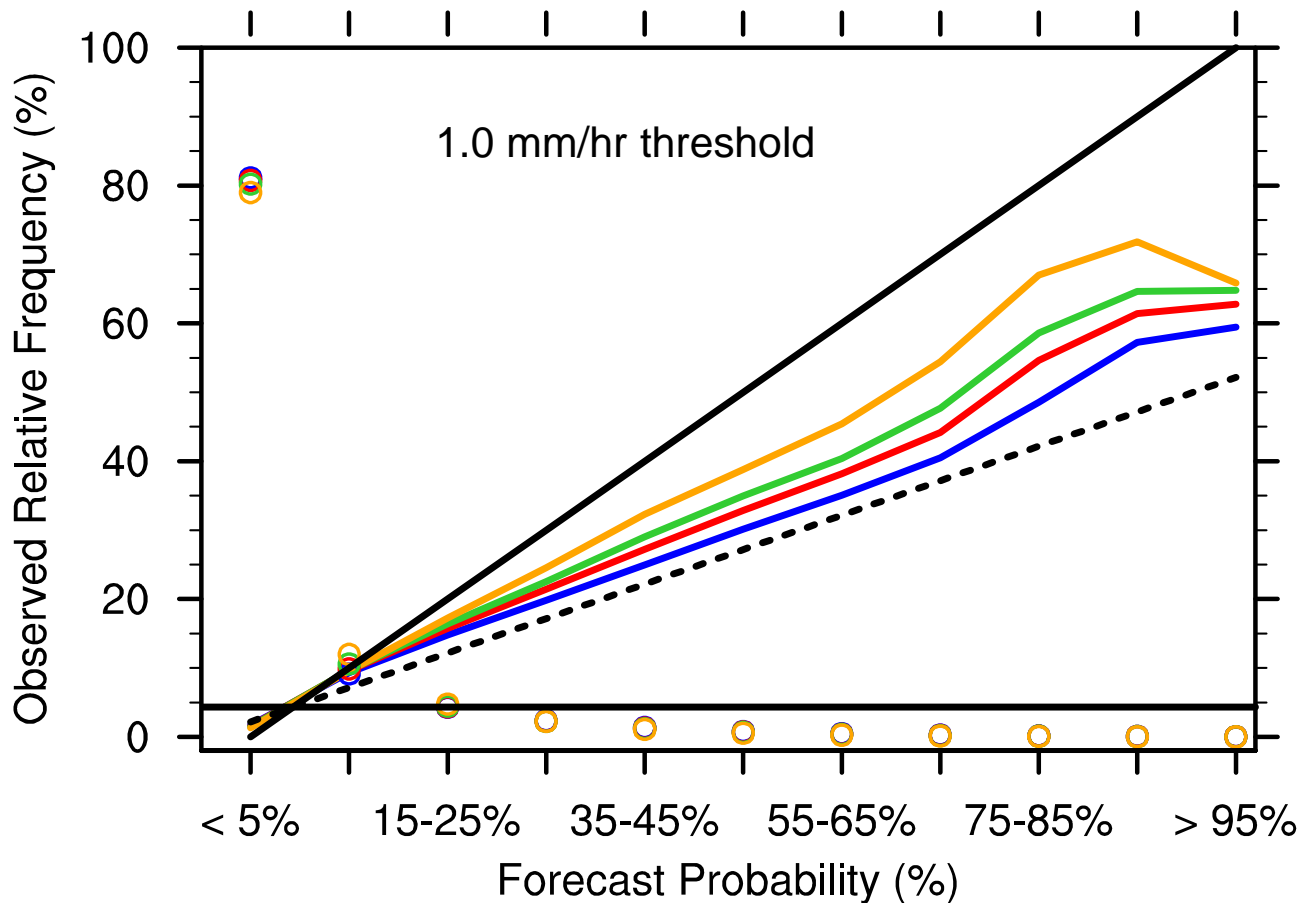
Observations



Average 12-36-hr precipitation (mm)

NCAR ensemble calibration

- Attributes diagrams for 18-36-hr precipitation over ~90 forecasts

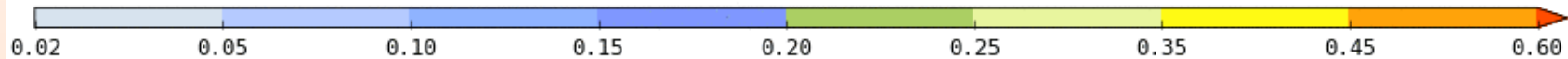
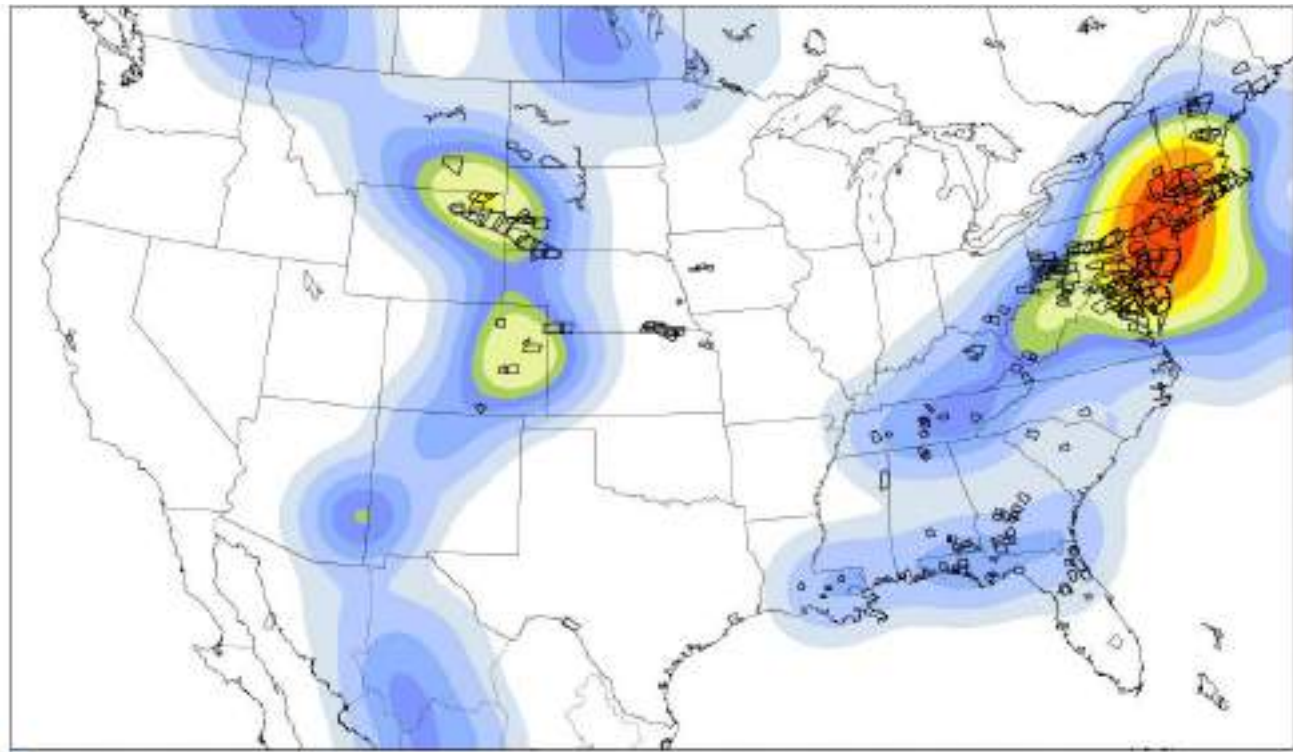


- Grid scale (i.e., 0-km radius of influence)
- 25-km radius of influence
- 50-km radius of influence
- 100-km radius of influence

Severe weather guidance

- Smoothed probabilities of the *union* of hail > 1 inch, wind exceeding 25 m/s, and intense mid-level rotation within 25 miles of a point within a 24-hr period

June 23, 2015

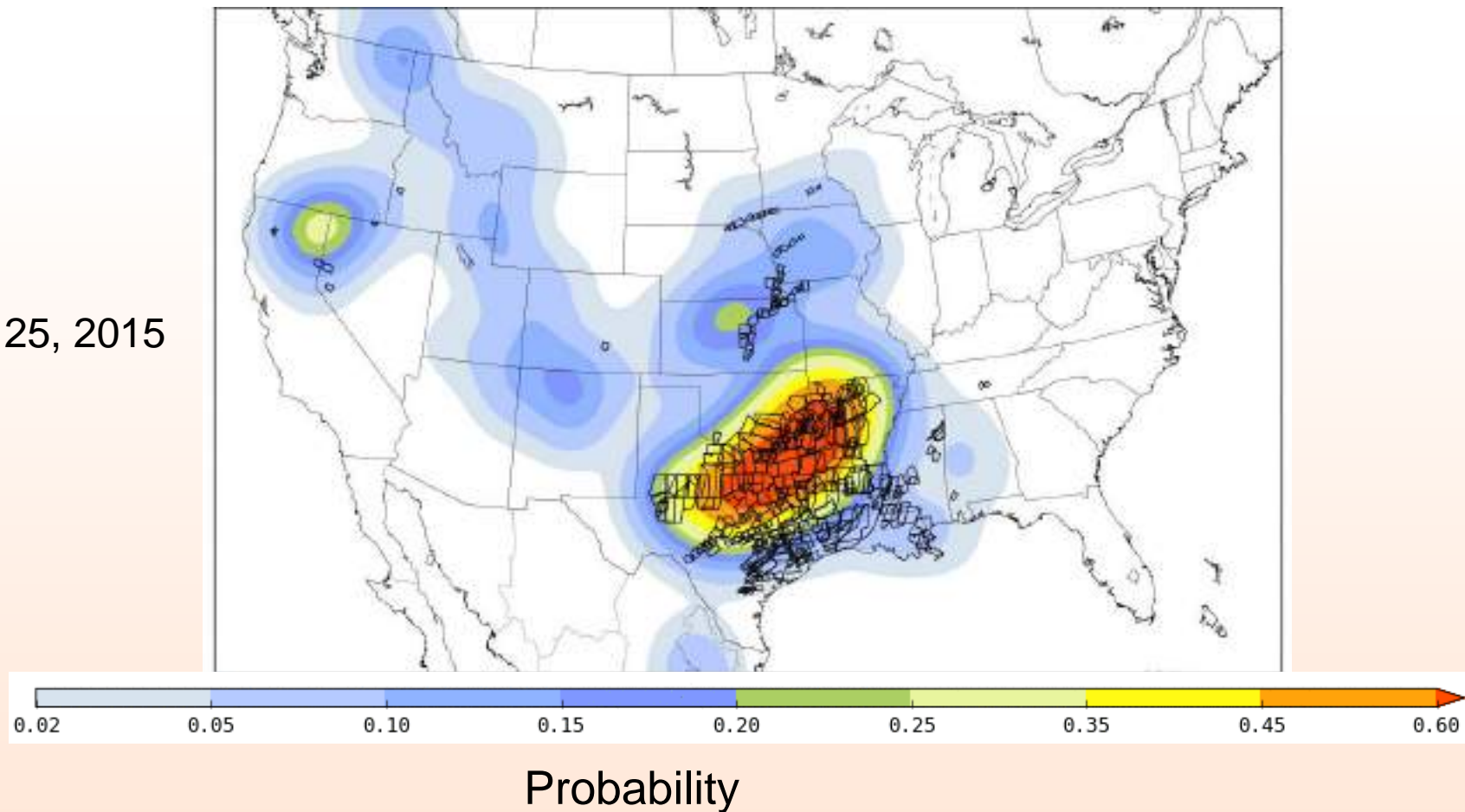


Probability

Severe weather guidance

- Smoothed probabilities of the *union* of hail > 1 inch, wind exceeding 25 m/s, and intense mid-level rotation within 25 miles of a point within a 24-hr period

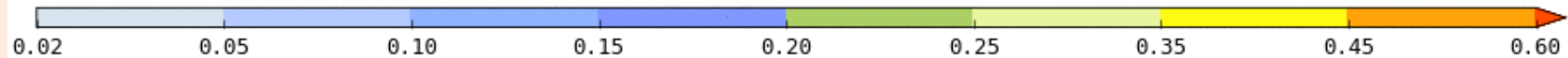
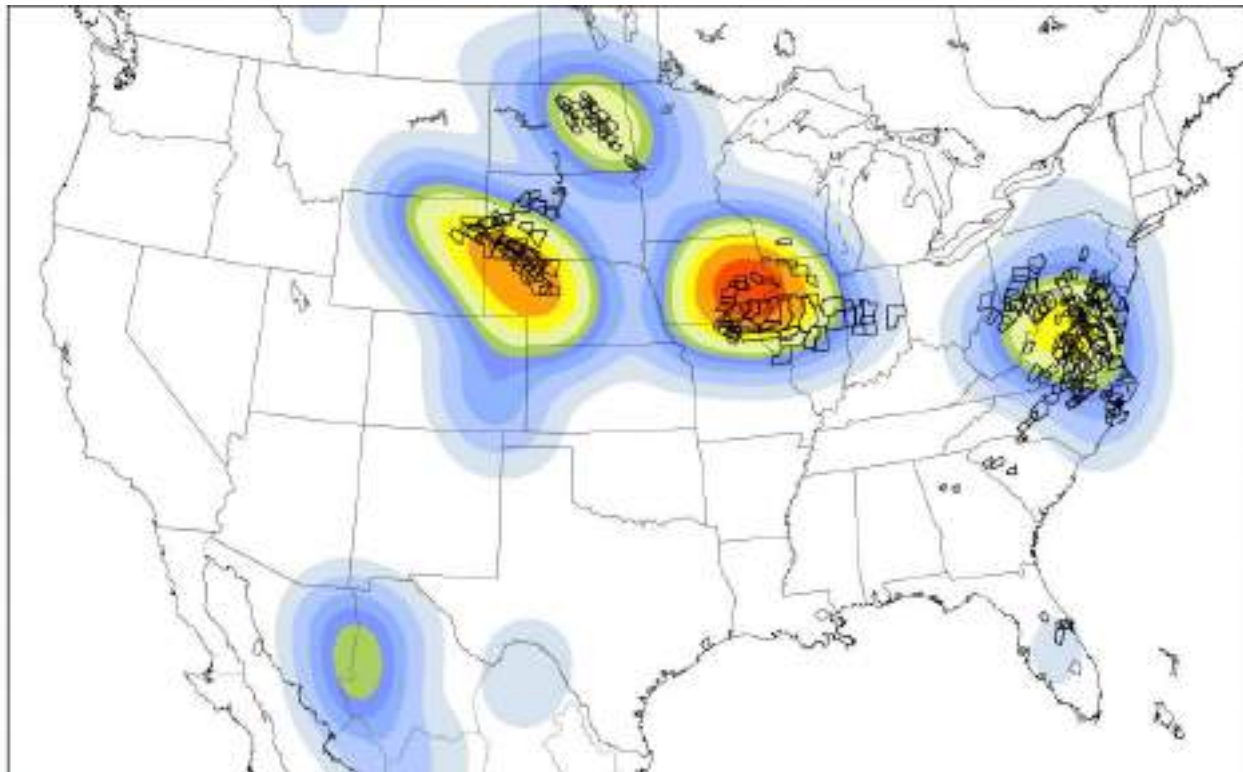
May 25, 2015



Severe weather guidance

- Smoothed probabilities of the *union* of hail > 1 inch, wind exceeding 25 m/s, and intense mid-level rotation within 25 miles of a point within a 24-hr period

June 20, 2015



Probability

Closing thoughts

- High-resolution ensembles are the future
- Development at operational centers worldwide
- Challenges
 - Optimal ensemble design?
 - How to get well-calibrated forecasts?
 - How to best use the ensemble output?
 - How many members are necessary?
- Expect much effort on these topics in upcoming years